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PTO/SR/61 (11-03)

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Docket Number (Optional)

ION FOR REVIVAL OF AN APPLICATION FOR PATENT ABANDONED **UNAVOIDABLY UNDER 37 CFR 1.137(a)**

First Named Inventor:

David S. Gilbert, Jr.

3723 Art Unit:

Application Number:

09/809/709

Examiner: Smith, James G.

OFFICE OF PETITIONS

Filed:

3/15/2001

Title:

Slide Lock Wrench

Attention: Office of Petitions

Mail Stop Petition

Commissioner for Patents

P.O. Box 1450

Alexandria, VA 22313-1450

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The above-identified application became abandoned for failure to file a timely and proper reply to a notice or action by the United Sates Patent and Trademark Office. The date of abandonment is the day after the expiration date of the period set for reply in the Office notice or action plus any extensions of time actually obtained

APPLICANT HEREBY PETITIONS FOR REVIVAL OF THIS APPLICATION.

NOTE: A grantable petition requires the following items:

Petition fee.

is enclosed herewith.

- Reply and/or issue fee. (2)
- Terminal disclaimer with disclaimer fee-required for all utility and plant applications filed (3)
 - before June 8, 1995, and for all design applications; and
- Adequate showing of the cause of unavoidable delay. (4)

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	Small entity – fee \$See 37 CFR 1.27.	_ (37 CFR 1.17(I))	. Applicant claims small entity status.
•	Other than small entity – fee \$_	(37 C	FR 1.17(I)).
2. Reply	and/or fee		
A.	The reply and/or fee to the above-note A type written reply	d Office action in th	ne form of (identify the type of reply):
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[Page 1 of 3]

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This collection of information is required by 37 CFR 1.137(a). The information is required to obtain or retain a benefit by the public which is to file (and by the USPTO to process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 CFR 1.14. This collection is estimated to take 8 hours to complete, including gathering, preparing, and submitting the completed application form to the USPTO. Time will vary depending upon the individual case. Any comments on the amount of time you require to complete this form and/or suggestions for reducing this burden, should be sent to the Chief Information Officer, U.S. Patent and Trademark Office, U.S. Department of Commerce, P.O. Box 1450, Alexandria, VA 22313-1450. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. SEND TO: Mail Stop Petition. Commissioner for Patents, P.O. Box 1450, Alexandria, VA 22313-1450. If you need assistance in completing the form, call 1-800-PTO-9199 and select option 2.



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3. Terminal dis	sclaimer with disclaimer fe	9 0			
	Since this utility/plant	Since this utility/plant application was filed on or after June 8, 1995, no terminal disclaimer is required.			
	A terminal disclaimer (and disclaimer fee (37 CFR 1.20(d)) of \$ for a small entity or \$ for other than a small entity) disclaiming the required period of time is enclosed herewith (see PTO/SB/63).				
An adequate for the reply	e showing of the cause of until the filing of a grants	f the delay, and that the entire delay in filing the required reply from the due date able petition under 37 CFR 1.137(a) was unavoidable, is enclosed.			
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12	/22/2003	David S. Gilbert Jr.			
	Date	Signature			
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I hereby certify that this correspondence is being: deposited with the United States Postal Service on the date shown below with sufficient postage as first class mail in an envelope addressed to Mail Stop Petition, Commissioner for Patents, P.O. Box 1450, Alexandria, VA 22313-1450.					
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PETITION FOR REVIVAL OF AN APPLICATION FOR PATENT ABANDONED **UNAVOIDABLY UNDER 37 CFR 1.137(a)**

NOTE:	OTE: The following showing of the cause of unavoidable delay must be signed by all applicants or by party who is presenting statements concerning the cause of delay.		
		David S. Gilbert In	
12/22/2003 Date	12/22/2003	Signature	
	David S. Gilbert, Jr.		
Reg	istration Number, if applicable	Typed or printed name	

(In the space provided below, please explain in detail the reasons for the delay in filing a proper reply.)

Mr. James G. Smith:

Dear Mr. Smith,

In accordance with our telephone conversation on Thursday, December 18, 2003 regarding your office not receiving my reply to your Office Action communication dated 12/13/2002, I have enclosed copies of all the papers sent to your office by me on 4/09/2003 via US Express Mail and a copy of the US Express Mail Receipt which is enclosed.

Since your office did not receive my transmittal sent by me by US Express Mail on 4/09/2003, the US Postal Service must have lost the express mail package or they would have delivered it to your office or at least returned it to me since my return address and telephone nmber are on the receipt and likewise on the address label affixed to the express mail envelope. The express mail envelope and it's contents were processed and mailed at my local US Post Office (15135) by their clerk identified on the express mail receipt.

Additionally, I did not contact you to learn what progress your office was making to resolve the Final Action in your 12/13/2002 communication because I felt you were very busy and I did not want to disturb you.

Hopefully you can now review the enclosed documents for a favorable decision on my behalf. I am still able to travel to your office to discuss any corrections that may be required after your review of the enclosed documents to make my invention patentable and better protected.

Thank you for your consideration.

Very truly yours,

David S. Gilbert & David S. Gilbert, Jr.

(Please attach additional sheets if additional space is needed.)



SLIDE LOCK WRENCH

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BACKGROUND OF THE INVENTION

1. Field of the Invention

This invention relates to wrenches and, more particularly, to wrenches which

are usable to handle various types and sizes of hexagonal, square and round work

pieces, particularly, nuts, bolts, pipes and pipe fittings.

2. Description of the Prior Art

A variety of hand tools have been utilized with the installation of nuts, bolts, pipes and pipe fittings. Wrench-type and plier-type hand tools are commonly used to handle nuts, bolts, pipes and pipe fittings. See, for example, the tools shown in United States Patents Nos. 994,070; 1,027,203; 1,199,806; 2,592,927; 3,968,708; 3,955,450; 2,882,774; 993,504; 1,586,513; 4,616,536; and 1,396,576.

However, the use of these prior art tools to install or remove nuts, bolts, pipes and pipe fittings is disadvantageous for numerous reasons. First, the opposing jaw areas allow a loose application at only two surfaces of the nuts and bolts of various sizes and shapes. In addition, these tools do not provide a uniform holding grip on the nuts or bolts. Further, these tools require a laborious task of repetitious mechanical adjustment and employing the use of various thumb and finger type devices to move the jaws of the tools to encompass the nuts and bolts. The same laborious task of repetitious mechanical adjustment is required to open the jaws to receive the nuts and bolts of various sizes and shapes. In the installation or removal of pipes and pipe fittings, the tools presently in use also require a laborious task of repetitious mechanical adjustment, employing the use of various thumb and finger type devices, to move the jaws of the tools to grasp the various sizes of pipes and pipe fittings. The same laborious task of repetitious mechanical adjustment is also required to open the jaws to receive the pipes and pipe fittings of various sizes and shapes.

Accordingly, it is the object of the present invention to provide wrenches for handling nuts, bolts, pipes and pipe fittings, which can be used to tighten or loosen the nuts, bolts, pipes and pipe fittings, with a uniform holding grip, without the laborious task of repetitious mechanical adjustment. It is another object of the invention to provide wrenches which can be easily used in a confined environment without damage to the nuts, bolts, pipes and pipe fittings themselves.

SUMMARY OF THE INVENTION

The present invention provides a wrench hand tool for the installation and removal of nuts, bolts, pipes, pipe fittings, rods and bars, with a uniform positive gripping action, without the laborious task of a repetitious mechanical adjustment as required by the wrench-type and plier-type hand tools of prior art.

BRIEF DESCRIPTION OF THE DRAWINGS

- Fig. 1 is a perspective view of the wrench according to the present invention;
- Fig. 2 is a perspective view of a second embodiment of the wrench according to the present invention;
 - Fig. 3 is a front view of the wrench shown in Fig. 1 grasping a hexagon shaped nut;
 - Fig. 4 is a right side view of the wrench shown in Fig. 3;
 - Fig. 5 is a left side view of the wrench shown in Fig. 3;
- Fig. 6 is a front view of the wrench as shown in Fig. 2 grasping a circular object;
 - Fig. 7 is a right side view of the wrench shown in Fig. 6;
 - Fig. 8 is a left side view of the wrench shown in Fig. 6;
- Fig. 9 is a front view of a third embodiment of the wrench, grasping a hexagon shaped nut, according to the present invention;
 - Fig. 10 is a right side view of the wrench shown in Fig. 9;
 - Fig. 11 is a left side view of the wrench shown in Fig. 9;

Fig. 12 is a front view of a fourth embodiment of the wrench, grasping a hexagon shaped nut, according to the present invention;

Fig. 13 is a right side view of the wrench shown in Fig. 12;

Fig. 14 is a left side view of the wrench shown in Fig. 12;

Fig. 15 is a top view of the wrench shown in Fig. 3;

Fig. 16 is a bottom view of the wrench shown in Fig. 3;

Fig. 17 is a top view of the wrench shown in Fig. 6;

Fig. 18 is a bottom view of the wrench shown in Fig. 6;

Fig. 19 is a top view of the wrench shown in Fig. 9;

10 Fig. 20 is a bottom view of the wrench shown in Fig. 9;

Fig. 21 is a top view of the wrench shown in Fig. 12;

Fig. 22 is a bottom view of the wrench shown in Fig. 12;

Fig. 23 is a sectional view of Fig. 24;

Fig. 24 is a left side view of Fig. 23;

15 Fig. 25 is a sectional view of Fig. 26;

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Fig. 26 is a left side view of Fig. 25;

Fig. 27 is a sectional view of Fig. 3;

Fig. 28 is a sectional view of Fig. 6;

Fig. 29 is an enlarged view of Fig. 27 and Fig. 28;

Fig. 30 displays hexagon shaped nuts and pipe fittings of several sizes;

Fig. 31 displays bolts and pipes of several sizes.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

Referring now to Figs. 1 thru 31, there is shown a wrench 1 for handling hex angular nuts 30 and hex angular bolts 31, as shown in Figs. 1, 3, 4, 5, 15, 16, 23, 24, 27, 29, 30 and 31. The wrench 1 includes a body 2, a pivoted lever handle 3, an upper angular gripping slidable jaw 4, a lower angular gripping movable jaw 5, and a serrated thumb slide 6. The body 2 and the pivoted handle 3 may have plastic or

other composition hand grips 7 there about which permit comfortable control of the wrench 1. The pivoted lever handle 3, having a cam means 29, is attached to the body 2 by a pivot 8. The angular jaw 4 and the angular jaw 5 are oriented to securely grasp a nut 30 or bolt 31 on four surfaces of the work piece there between. The wrench 1 may be constructed of drop-forged steel, stamped metal, powdered metal or other adequate strength materials.

The wrench 1 is usable to tighten or loosen nuts 30 and bolts 31 by moving the jaw 4 toward the jaw 5, thereby grasping the nut 30 or bolt 31 therein. The jaw 4 may be moved toward the jaw 5 by applying force to the jaw 4 on the serrated areas 10 9 or 10, by sliding the serrated thumb pull 6 or by cranking the handle 3 towards the body 2. Referring to Figs. 23 and 29, the handle 3 is held in a neutral position by a retaining spring 33. Cranking the handle 3 towards the body 2 causes the pivot 43 to move the link 45 in a downward motion causing the pivoted notched device 35, which is held in constant position against the outer side surface ratcheted teeth 48 of the 15 upper jaw 4 by the retaining spring 34, to move the jaw 4 to the desired position towards the jaw 5 to engage the nut 30 or bolt 31. Moving the jaw 4 towards the jaw 5 causes the notched dog 36, which is also held in constant position by the retaining. spring 34, to engage the ratcheted teeth 48 on the jaw 4 thereby locking the jaw 4 in a positive position. Grasping the handle 3 toward the body 2, while the jaw 4 is in a 20 locked position, causes a cam lever action at the end portion 29 of the handle 3 against the jaw 5 thereby causing a positive gripping force against the nut 30 or the bolt 31. The nut 30 or bolt 31 may then be rotated clockwise or counterclockwise without inverting the wrench 1. Releasing the grasp on the handle 3 and moving the handle 3 away from the body 2 beyond the neutral position, allows the pivot pin 44 to 25 move the link 46 away from the body 2 and pulls the pivot pin 40 on the notched dog 36, which revolves on pivot pin 39, thus moving the notched dog 36 away from the ratcheted teeth 48 and simultaneously allows the pivot pin 43 to move the link 45

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away from the body 2 and pulls the pivot pin 38 on the notched device 35 thus moving the notched device 35 away from the ratcheted teeth 48 thus allowing the compression spring 42 to return the jaw 4 to a fully open position.

The upper portion of jaws 4 and 5 are formed substantially as hex angular

gripping surface areas 16, divided by circular grooves 15, to accommodate obtrusive irregularities on the outside corners of some hex angular nuts and bolts. The hex angular gripping surface areas 16 are arranged to grasp the angular surfaces of hex angular nuts 30 and bolts 31 as shown in Figs. 3, 30 and 31. The jaw 5 contains thereon alignment appendages 11 which allow the jaw 5 to move parallel in the

alignment slits 12 thus allowing the cam action 29 to tighten the jaw 5 against the nut 30 or bolt 31 as shown in Fig. 3. The jaw 4 contains therein alignment slits 47, which ride along the alignment pins 14 to maintain alignment of the jaw 4 as it travels back and forth in the body pocket chamber 37 as the notched dog 36 and notched device 35 engage or disengage the ratcheted teeth 48 on the jaw 4 as shown in Figs. 23, 27 and 29. The lower body portion contains therein a body chamber 37 to house a coil spring 42 to maintain constant pressure against the lower portion of jaw 4 as shown in Figs. 23, 27 and 29.

The first preferred embodiment of the wrench 1 is fully described above. A second preferred embodiment of the wrench 1 for handling pipes 49 and pipe fittings 50 is shown in Figs. 2, 6, 7, 8, 17, 18, 25, 26, 28, 29, 30 and 31. The wrench 1 includes a body 2, a pivoted lever handle 3 and serrated gripping surfaces 21 on jaws 17 and 18 for grasping pipes 49 and pipe fittings 50. The wrench 1 is usable to tighten or loosen pipes 49 and pipe fittings 50 by moving the jaw 17 toward the jaw 18, thereby grasping the pipes 49 and pipe fittings 50 therein. The jaw 17 may be moved toward the jaw 18 by applying force to the jaw 17 on the serrated areas 19 or 20, by sliding the serrated thumb pull 6 or by cranking the handle 3 towards the body 2. When the jaws 17 and 18 engage the pipe 49 or pipe fitting 50, grasping the

handle 3 towards the body 2 causes the cam lever action at the end portion 29 thereby causing a positive tightening of the jaw 18 against the jaw 17 thus causing a positive gripping force on the pipe 49 or pipe fitting 50. Releasing the grasp on the handle 3, allows the wrench 1 to rotate on the pipe 49 or fitting 50 in a repetitive manner without removing the wrench 1 from the work piece. Removing the pipes 49 and pipe fittings 50 is accomplished by inverting the wrench 1 on the pipes 49 and pipe fittings 50 and rotating the wrench 1 in a counterclockwise direction thus removing the work piece.

A third preferred embodiment of the wrench 1 for handling hex angular nuts is shown in Figs. 9, 10, 11, 19, 20, 30 and 31. The wrench 1 includes a body 2, a pivoted lever handle 3, serrated angular gripping surfaces 24 on movable jaws 22 and 23 for grasping damaged or irregular shaped objects such as, but not limited to, nuts, bolts, pipes, fittings, rods and bars. The wrench 1 is usable to tighten or loosen work pieces by moving the jaw 22 toward the jaw 23, thereby grasping the work piece therein. The jaw 22 may be moved toward the jaw 23 by applying force to the jaw 22 on the serrated areas 9 or 10, by sliding the serrated thumb pull 6, or by cranking the handle 3 towards the body 2. When the jaws 22 and 23 engage the work piece, grasping the lever handle 3 towards the body 2 causes a cam lever action at the end portion 29 against jaw 23 thereby causing a positive gripping force against the work piece. The work piece may then be rotated clockwise or counterclockwise without inverting the wrench 1.

A fourth preferred embodiment of the wrench 1 for handling hex angular and square nuts as shown in Figs. 12, 13, 14, 21, 22, 30 and 31. The wrench 1 includes a body 2, a pivoted lever handle 3, opposing parallel aligned gripping surfaces 27 on movable jaws 25 and 26 for grasping hex angular and square nuts. The wrench 1 is usable to tighten or loosen work pieces by moving the jaw 25 toward the jaw 26, thereby grasping the work piece therein. The jaw 25 may be moved toward the jaw

26 by applying force to the jaw 25 on the serrated area 28, by sliding the serrated thumb pull 6, or by cranking the handle 3 towards the body 2. When the jaws 25 and 26 engage the work piece, grasping the handle 3 towards the body 2 causes the cam lever action at the end portion 29 against jaw 26 thereby causing a positive gripping force against the work piece. The work piece may then be rotated clockwise or counterclockwise without inverting the wrench 1.

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Having described above the presently preferred embodiments of the present invention, it is to be understood that the invention may be otherwise embodied within the scope of the appended claims.

I claim:

1. A hand tool for handling a work piece, comprising:

a body portion having therein an adjustable upper angular gripping slidable jaw portion oriented to securely grasp a work piece therein, having provided thereon an extended member containing an outer side surface of ratcheted teeth, and a spring actuated notched dog pivoted in a body pocket chamber to engage said ratcheted teeth and means for holding said upper angular gripping slidable jaw portion in a cooperative position;

an opposing lower angular gripping movable jaw portion in said body pocket chamber

thereof, oriented to securely grasp said work piece therein; and

a pivoted lever handle therein, having thereon a cam shaped end, held in a neutral

position in said body pocket chamber by a retaining spring, when grasped and moved
towards said body portion in a cranking motion, moves a connected link held in

tension by a spring in said body pocket chamber, in a downward position causing a

second connected pivoted notched device in said body pocket chamber, held in

second connected pivoted notched device in said body pocket chamber, held in constant position by a second retaining spring in said body pocket chamber, to engage said teeth of said upper angular gripping slidable jaw portion to move said upper angular gripping slidable jaw portion to a desired position towards said opposing lower angular gripping movable jaw portion thereby engaging said work

20 piece firmly between said opposing upper angular gripping slidable jaw and lower angular gripping slidable jaw; and

a cam action means on said lever handle cam shaped end, urges said lower angular gripping movable jaw portion to exert positive gripping force on said work piece therein; and

25 releasing said grasp on said lever handle and moving said lever handle away from said body portion beyond said neutral position, releases said spring actuated pivoted notched dog and said pivoted notch device away from said upper angular gripping

slidable jaw ratcheted teeth, allowing a compression spring means in said body pocket chamber to move said upper angular gripping slidable jaw portion away from said work piece and said opposing lower angular gripping movable jaw portion to a fully open position whereby allowing the operator of said hand tool means to disengage said hand tool from said work piece quickly to engage other work pieces of various sizes.

- 2. The hand tool of claim 1 wherein said work pieces may be hex nuts having obtrusive irregularities at the intersections of its hex-angular surfaces, whereby a groove is adapted at the intersection of the inner surfaces of the said upper angular gripping slidable jaw portion and said lower angular gripping movable jaw portion to receive said obtrusive irregularities of said work piece on said jaw gripping areas.
- 3. The hand tool of claim 1 wherein said adjustable upper angular gripping slidable jaw portion contains serrated areas on the top outer surfaces thereon means allowing a non-slipping action when applying force to move said adjustable upper angular gripping slidable jaw portion to apply force to move said adjustable upper angular gripping slidable jaw portion towards said lower angular gripping movable jaw portion to engage said work piece firmly between said adjustable upper angular gripping, slidable jaw portion and said lower angular gripping movable jaw portion.
- 4. The hand tool of claim 1 wherein said adjustable upper angular gripping slidable jaw portion contains thereon serrated thumb pulls means for applying force to move said upper angular gripping slidable jaw portion towards said lower angular gripping movable jaw portion to engage said work piece firmly between said upper angular gripping slidable jaw portion and said lower angular gripping movable jaw portion.
- 5. The hand tool of claim 1 wherein said lower angular gripping movable jaw portion contains thereon alignment appendages means to allow said lower angular gripping movable jaw portion to move parallel in alignment slits in said body allowing said cam action means to exert said positive gripping force on said work piece therein.

- 6. The hand tool of claim 1 wherein pivot pins means connect links to said pivoted lever handle, said notched dog and said pivoted notched device.
- 7. The hand tool of claim 1 wherein pivot pin means connect said pivoted lever handle to said body.
- 8. The hand tool of claim 1 wherein body alignment pins means allow said upper angular gripping slidable jaw portion to move parallel within alignment slits in said body portion.
- 9. The hand tool of claim 1 wherein said work pieces may be pipes and pipe fittings,
 whereby said upper gripping slidable jaw portion and opposing said lower gripping
 movable jaw portion have serrated gripping surface means for handling round work
 pieces.
 - 10. The hand tool of claim 1 wherein said work pieces may be damaged or irregular in shape, whereby said upper angular gripping slidable jaw portion and opposing said lower angular gripping movable jaw portion have serrated gripping surface means for

15 handling said work pieces.

11. The hand tool of claim 1 wherein said work pieces may be hex angular or square, whereby said upper slidable gripping jaw portion and opposing said lower movable gripping jaw portion have opposing smoothe gripping surface means for handling said work pieces.

SLIDE LOCK WRENCH

ABSTRACT OF THE DISCLOSURE

A quick sliding adjustable locking wrench is disclosed having slidable and movable opposing jaw areas for engaging and gripping hex angular, round, square or irregular work pieces of various sizes within its operating capacity. A quick release jaw mechanism, employed within the wrench, allows the operator of the wrench, rapid release of the jaws from the work piece, to continue on to the next work piece engagement. The jaw portions are additionally configured to firmly grip and lock on to the various work pieces.



SLIDE LOCK WRENCH

BACKGROUND OF THE INVENTION

1. Field of the Invention

This invention relates to wrenches and, more particularly, to wrenches which are usable to handle various types and sizes of hexagonal, square and round work pieces, particularly, nuts, bolts, pipes and pipe fittings.

2. Description of the Prior Art

shapes.

A variety of hand tools have been utilized with the installation of nuts, bolts, pipes and pipe fittings. Wrench-type and plier-type hand tools are commonly used to handle nuts, bolts, pipes and pipe fittings. See, for example, the tools shown in United States Patents Nos. 994,070; 1,027,203; 1,199,806; 2,592,927; 3,968,708; 3,955,450; 2,882,774; 993,504; 1,586,513; 4,616,536; and 1,396,576.

However, the use of these prior art tools to install or remove nuts, bolts, pipes and pipe fittings is disadvantageous for numerous reasons. First, the opposing jaw areas allow a loose application at only two surfaces of the nuts and bolts of various sizes and shapes. In addition, these tools do not provide a uniform holding grip on the nuts or bolts. Further, these tools require a laborious task of repetitious mechanical adjustment and employing the use of various thumb and finger type devices to move the jaws of the tools to encompass the nuts and bolts. The same laborious task of repetitious mechanical adjustment is required to open the jaws to receive the nuts and bolts of various sizes and shapes. In the installation or removal of pipes and pipe fittings, the tools presently in use also require a laborious task of repetitious mechanical adjustment, employing the use of various thumb and finger type devices, to move the jaws of the tools to grasp the various sizes of pipes and pipe fittings. The same laborious task of repetitious mechanical adjustment is also required to open the jaws to receive the pipes and pipe fittings of various sizes and

Accordingly, it is the object of the present invention to provide wrenches for handling nuts, bolts, pipes and pipe fittings, which can be used to tighten or loosen the nuts, bolts, pipes and pipe fittings, with a uniform holding grip, without the laborious task of repetitious mechanical adjustment. It is another object of the invention to provide wrenches which can be easily used in a confined environment without damage to the nuts, bolts, pipes and pipe fittings themselves.

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SUMMARY OF THE INVENTION

The present invention provides a wrench hand tool for the installation and removal of nuts, bolts, pipes, pipe fittings, rods and bars, with a uniform positive gripping action, without the laborious task of a repetitious mechanical adjustment as required by the wrench-type and plier-type hand tools of prior art.

BRIEF DESCRIPTION OF THE DRAWINGS

- Fig. 1 is a perspective view of the wrench according to the present invention;
- Fig. 2 is a perspective view of a second embodiment of the wrench according to the present invention:
 - Fig. 3 is a front view of the wrench shown in Fig. 1 grasping a hexagon shaped nut;
 - Fig. 4 is a right side view of the wrench shown in Fig. 3;
 - Fig. 5 is a left side view of the wrench shown in Fig. 3;
- Fig. 6 is a front view of the wrench as shown in Fig. 2 grasping a circular object;
 - Fig. 7 is a right side view of the wrench shown in Fig. 6;
 - Fig. 8 is a left side view of the wrench shown in Fig. 6;
- Fig. 9 is a front view of a third embodiment of the wrench, grasping a hexagon shaped nut, according to the present invention;
 - Fig. 10 is a right side view of the wrench shown in Fig. 9;
 - Fig. 11 is a left side view of the wrench shown in Fig. 9:

- Fig. 12 is a front view of a fourth embodiment of the wrench, grasping a hexagon shaped nut, according to the present invention;
 - Fig. 13 is a right side view of the wrench shown in Fig. 12;
 - Fig. 14 is a left side view of the wrench shown in Fig. 12;
- 5 Fig. 15 is a top view of the wrench shown in Fig. 3;
 - Fig. 16 is a bottom view of the wrench shown in Fig. 3;
 - Fig. 17 is a top view of the wrench shown in Fig. 6;
 - Fig. 18 is a bottom view of the wrench shown in Fig. 6;
 - Fig. 19 is a top view of the wrench shown in Fig. 9;
- 10 Fig. 20 is a bottom view of the wrench shown in Fig. 9;
 - Fig. 21 is a top view of the wrench shown in Fig. 12;
 - Fig. 22 is a bottom view of the wrench shown in Fig. 12;
 - Fig. 23 is a sectional view of Fig. 24;
 - Fig. 24 is a left side view of Fig. 23;
- 15 Fig. 25 is a sectional view of Fig. 26;
 - Fig. 26 is a left side view of Fig. 25;
 - Fig. 27 is a sectional view of Fig. 3;
 - Fig. 28 is a sectional view of Fig. 6;
 - Fig. 29 is an enlarged view of Fig. 27 and Fig. 28;
- 20 Fig. 30 displays hexagon shaped nuts and pipe fittings of several sizes;
 - Fig. 31 displays bolts and pipes of several sizes.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

Referring now to Figs. {1-31}, there is shown a wrench {1} for handling hex angular nuts {30} and hex angular bolts {31}, as shown in Figs. 1, 3, 4, 5, 15, 16, 23, 24, 27, 29, 30 and 31. The wrench {1} includes a body {2}, a pivoted lever handle {3}, an upper angular gripping {movable} jaw {4}, a lower angular gripping movable jaw {5}, and a serrated thumb slide {6}. The body {2} and the pivoted handle {3} may have plastic or other composition hand grips {7} there about which permit comfortable control of the wrench (). The pivoted lever handle {3}, having a cam means {29}, is attached to the body {2} by a pivot {8}. The angular jaw {4} and the angular jaw {5} are oriented to securely grasp a nut {30} or bolt {31} on four surfaces of the {workpiece} there between. The wrench {1} may be constructed of drop-forged steel, stamped metal, powdered metal or other adequate strength materials.

The wrench () is usable to tighten or loosen nuts {30} and bolts {31} by moving the jaw {4} toward the jaw {5}, thereby grasping the nut {30} or bolt {31} therein. The jaw {4} may be moved toward the jaw {5} by applying force to the jaw {4} on the serrated areas {9} or {10}, by sliding the serrated thumb pull {6} or by cranking the handle {3} towards the body {2}. Referring to Figs. 23 and 29, the handle {3} is held in a neutral position by a retaining spring {33}. Cranking the handle {3} towards the body {2} causes the pivot {43} to move the link {45} in a downward motion causing the pivoted notched device {35}, which is held in constant position against the outer side surface {racheted} teeth {48} of the upper jaw {4} by the retaining spring {34}, to move the jaw {4} to the desired position towards the jaw 5 to engage the nut {30} or bolt {31}. Moving the jaw {4} towards the jaw {5} causes the notched dog {36}, which is also held in constant position by the retaining spring {34}, to engage the {ratchet} teeth {48} on the jaw {4} thereby locking the jaw {4} in a positive position. Grasping the handle {3} toward the body {2}, while the jaw {4} is in a locked position, causes a cam lever action at the end portion {29} of the handle {3} against the jaw {5} thereby

causing a positive gripping force against the nut {30} or the bolt {31}. The nut {30} or bolt {31} may then be rotated clockwise or counterclockwise without inverting the wrench (). Releasing the grasp on the handle {3} and moving the handle {3} away from the body {2} beyond the neutral position, allows the pivot pin {44} to move the link {46} away from the body {2} and pulls the pivot pin {40} on the notched dog {36}, which revolves on pivot pin {39}, thus moving the notched dog {36} away from the {notches} {48} and simultaneously allows the pivot pin {43} to move the link {45} away from the body {2} and pulls the pivot pin {38} on the notched device {35} thus moving the notched device {35} away from the {notches} {48} thus allowing the compression 10 spring {42} to return the jaw {4} to a fully open position.

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The upper portion of jaws {4} and {5} are formed substantially as hex angular gripping surface areas {16}, divided by circular grooves {15}, to accommodate obtrusive irregularities on the outside comers of some hex angular nuts and bolts. The hex angular gripping surface areas {16} are arranged to grasp the angular 15 surfaces of hex angular nuts (30) and bolts (31) as shown in Figs. 3, 30 and 31. The jaw {5} contains thereon alignment appendages {11} which allows the jaw {5} to move {laterally} in the alignment slits {12} thus allowing the cam action {29} to tighten the jaw (5) against the nut (30) or bolt (31) as shown in Fig. 3. The jaw (4) contains therein alignment slits {47}, which ride along the alignment pins {14} to maintain 20 alignment of the jaw {4} as it travels back and forth in the body pocket chamber {37} as {the dog} {36} and notched device {35} engage or disengage the {ratchet} teeth {48} on the jaw {4} as shown in Figs. 23, 27 and 29. The lower body portion contains therein a body chamber {37} to house a coil spring {42} to maintain constant pressure against the lower portion of jaw {4} as shown in Figs. 23, 27 and 29.

The first preferred embodiment of the wrench () is fully described above. A second preferred embodiment of the wrench {1} for handling pipes {49} and pipe fittings {50} is shown in Figs. 2, 6, 7, 8, 17, 18, 25, 26, 28 [and] 29, 30 and 31. The wrench {1} includes a body {2}, a pivoted lever handle {3} and serrated gripping surfaces {21} on jaws {17} and {18} for grasping pipes {49} and pipe fittings {50}. The wrench () is usable to tighten or loosen pipes {49} and pipe fittings {50} by moving the jaw {17} toward the jaw {18}, thereby grasping the pipes {49} and pipe fittings {50}. 50 therein. The jaw {17} may be moved toward the jaw {18} by applying force to the jaw {17} on the serrated areas {19} or {20}, by sliding the serrated thumb pull {6} or by cranking the handle {3} towards the body {2}. When the jaws {17} and {18} engage the pipe {49} or pipe fitting {50}, grasping the handle {3} towards the body {2} causes the cam lever action at the end portion {29} thereby causing a positive tightening of the jaw {18} against the jaw {17} thus causing a positive gripping force on the pipe {49} or pipe fitting {50}. Releasing the grasp on the handle 3, allows the wrench () to rotate on the pipe {49} or fitting {50} in a repetitive manner without removing the wrench () from the {workpiece}. Removing the pipes {49} and pipe fittings {50} and rotating the wrench () in a counterclockwise direction thus removing the {workpiece}.

A third preferred embodiment of the wrench {1} for handling hex angular nuts is shown in Figs. 9, 10, 11, 19, 20, 30 and 31. The wrench () includes a body {2}, a pivoted lever handle {3}, serrated angular gripping surfaces {24} on movable jaws {22} and {23} for grasping damaged or irregular shaped objects such as, but not limited to, nuts, bolts, pipes, fittings, rods and bars. The wrench () is usable to tighten or loosen {workpieces} by moving the jaw {22} toward the jaw {23}, thereby grasping the {workpiece} therein. The jaw {22} may be moved toward the jaw {23} by applying force to the jaw {22} on the serrated areas {9} or {10}, by sliding the serrated thumb pull {6}, or by cranking the handle {3} towards the body {2}. When the jaws {22} and {23} engage the {workpiece}, grasping the lever handle {3} towards the body {2} causes a cam lever action at the end portion {29} against jaw {24} thereby causing a positive gripping force against the {workpiece}. The {workpiece} may then be rotated

clockwise or counterclockwise without inverting the wrench ().

A fourth preferred embodiment of the wrench {1} for handling hex angular and square nuts as shown in Figs. 12, 13, 14, 21, 22, 30 and 31. The wrench {1} includes a body {2}, a pivoted lever handle {3}, opposing parallel aligned (flat) gripping

5 surfaces {27} on movable jaws {25} and {26} for grasping hex angular and square nuts. The wrench () is usable to tighten or loosen {workpieces} by moving the jaw {25} toward the jaw {26}, thereby grasping the {workpiece} therein. The jaw {25} may be moved toward the jaw {26} by applying force to the jaw {25} on the serrated area {28}, by sliding the serrated thumb pull {6}, or by cranking the handle {3} towards the body {2}. When the jaws {25} and {26} engage the {workpiece}, grasping the handle {3} towards the body {2} causes the cam lever action at the end portion {29} against jaw {26} thereby causing a positive gripping force against the workpiece. The {workpiece} may then be rotated clockwise or counterclockwise without inverting the wrench ().

Having described above the presently preferred embodiments of the present invention, it is to be understood that the invention may be otherwise embodied within the scope of the appended claims.

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I claim:

- {1}. A hand tool for handling a work piece, comprising: {} a body portion having therein an adjustable upper {angular slidable} jaw portion oriented to securely grasp a {workpiece} therein, having provided thereon an extended member containing an
- outer side surface of ratcheted teeth, and a spring actuated notched dog pivoted in a {body chamber} to engage said ratcheted teeth and means for holding said upper {angular slidable} jaw portion in a cooperative position;
 - an opposing lower {angular movable} jaw portion in said {body thereof}, oriented to securely grasp said {workpiece} therein; and
- a pivoted lever handle therein, having thereon a cam shaped end, held in a neutral position in said {body chamber} by a retaining spring, when grasped and moved towards said {body in} a cranking motion, moves a connected link held in tension by a spring in said {body chamber}, in a downward position causing a second connected pivoted notched device in said body chamber, held in constant position by a second
- retaining spring in said {body chamber}, to engage said teeth of said upper {angular slidable} jaw portion to move said upper {angular slidable} jaw portion to a desired position towards said opposing lower {angular movable} jaw portion thereby engaging said {workpiece} firmly between said opposing upper {and lower jaws}; and [said] cam action means on said lever handle cam shaped end, urges said lower
- 20 {angular movable} jaw portion to exert positive gripping force on said {workpiece} therein; and {} releasing said grasp on said lever handle and moving said lever handle away from said body beyond said neutral position, releases said spring actuated pivoted notched dog and said pivoted notch device away from said upper {angular slidable} jaw {notches} allowing a compression spring means in said {body}
- 25 chamber} to move said upper {angular slidable} jaw portion away from said {workpiece} and said opposing lower {angular movable} jaw portion to a fully open position whereby allowing the operator of said hand tool means to disengage said

hand tool from said {workpiece} quickly to engage other {workpieces} of various sizes.

- {2}. The hand tool of claim 1 wherein said {workpieces} may be hex nuts having obtrusive irregularities at the intersections of its hex-angular surfaces, whereby a groove is adapted at the intersection of the inner surfaces of the said upper {angular slidable} jaw portion and said lower {angular movable} jaw portion to receive said obtrusive irregularities of said {workpiece} on said jaw gripping areas.
- {3}. The hand tool of claim 1 wherein said adjustable upper {angular slidable} jaw
 portion {contains thereon serrated areas on the outer surfaces means to apply force
 to move said upper angular slidable jaw portion towards said lower angular movable
 jaw portion to engage said workpiece firmly between said upper and lower jaws}.
- {4}. The hand tool of claim 1 wherein said adjustable upper {angular slidable} jaw.
 portion contains thereon serrated thumb pulls means for applying force to move said upper {angular slidable} jaw portion towards said lower {angular movable} jaw portion
 to engage said {workpiece} firmly between {said upper and lower jaws.}
 - {5}. The hand tool of claim 1 wherein said lower {angular movable} jaw portion contains thereon alignment appendages means to allow said lower {angular movable} jaw portion to move {laterally} in alignment slits in said body allowing said cam action means to exert said positive gripping force on said {workpiece} therein.
- 20 {6}. The hand tool of claim 1 wherein pivot pins means connect [said] links to said pivoted lever handle, said notched dog and {said notched} device.
 - {7}. The hand tool of claim 1 wherein pivot pin means connect said pivoted lever handle to said body.
- {8}. The hand tool of claim 1 wherein {body pins} means allow said upper {angularslidable} jaw portion to move {laterally with alignment slits therein}.
 - {9}. The hand tool of claim 1 wherein said {workpieces} may be pipes and pipe fittings, whereby said {upper jaw} portion and opposing said lower {movable jaw}

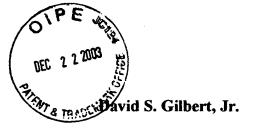
portion have slanted serrated gripping surface means for handling round {workpieces}.

- {10}. The hand tool of claim 1 wherein said {workpieces} may be damaged or irregular in shape, whereby said upper {angular slidable} jaw portion and opposing said lower {angular movable} jaw portion have serrated gripping surface means for handling said {workpieces}.
- {11}. The hand tool of claim 1 wherein said {workpieces} may be hex angular or square, whereby said upper {slidable jaw} portion and opposing said lower {movable jaw} portion {have flat} gripping surface means for handling said {workpieces}.

SLIDE LOCK WRENCH

ABSTRACT OF THE DISCLOSURE

A quick sliding adjustable locking wrench is disclosed having slidable and movable opposing jaw areas for engaging and gripping hex angular, round, square or irregular {work pieces} of various sizes within its operating capacity. A quick release jaw mechanism, employed within the wrench, allows the operator of the wrench, rapid release of the jaws from the {workpiece}, to continue on to the next {workpiece} engagement. The jaw portions are additionally configured to firmly grip and lock on to the various {work pieces}.



April 10, 2003

DEC 3 0 2003

OFFICE OF PETITIONS

James G. Smith
Patent Examiner
C/O Assistant Commissioner of Patents
Washington, District of Columbia 20231

Re: Application No. 09/809/709

Filing Date 03/15/2001 First Named Inventor: David S. Gilbert, Jr. Confirmation No. 4506

Dear Mr. Smith:

Enclosed please find "clean pages" 1 through 11 and "marked up" pages 1 through 11 of my patent application 09/809/709 corrected per your office communication dated 12/13/2002. Your records should show a one month extension of time was granted based on my request and the check that I forwarded to your office.

Because of my serious health problems these past 11 months, I have been receiving extensive radiology and chemotherapy under my Doctor's care at Allegheny General Hospital in Pittsburgh, and because of the pain and side effects I have been unable to arrange a personal interview with you to discuss the rejected items in your office action as well as the two previous office actions. Thankfully my cancer is now in remission, and I will now be able to travel to your office to discuss any corrections that may be required after your review of the enclosed documents, or if necessary changes are required, we may be able to discuss them by fax or by telephone.

Please be advised that I have used the designations [deletions], (added matter) and {amended once} for changes on the "marked up" pages.

Hopefully, I have made all the proper changes in the office action to your satisfaction and you will approve my patent as corrected. Additionally, I would appreciate any suggestion that you feel will make my claims stronger for my patent protection.

Very truly yours,

David S. Gilbert, Jr.



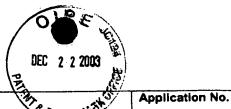
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ATTORNEY DOCKET NO. CONFIRMATION NO. FIRST NAMED INVENTOR APPLICATION NO. FILING DATE 4506 David S. Gilbert JR. 03/15/2001 09/809,709 EXAMINER 12/15/2003 7590 SMITH, JAMES G DAVID S. GILBERT, JR. 110 ROCK RUN ROAD ART UNIT PAPER NUMBER ELIZABETH, PA 15037-2350 3723 DEC 3 0 2003 DATE MAILED: 12/15/2003 OFFICE OF PETITIONS

Please find below and/or attached an Office communication concerning this application or proceeding.





Applicant(s)

RADIMAR	09/809,709	GILBERT, DAVID S.	
Notice of Abandonment	Examiner	Art Unit	
	James G. Smith	3723	

	James G. Smith	3723	
The MAILING DATE of this communication app	ears on the cover sheet with the c	orrespondence ad	dress_EIVEL
This application is abandoned in view of:			DEC 3 0 2003
 Applicant's failure to timely file a proper reply to the Office (a) A reply was received on (with a Certificate of Note of period for reply (including a total extension of time of) 	tailing or Transmission dated month(s)) which expired on _), which is after the	
(b) A proposed reply was received on, but it does			
(A proper reply under 37 CFR 1.113 to a final rejection application in condition for allowance; (2) a timely filed Continued Examination (RCE) in compliance with 37 to 20 compliance.	I Notice of Appeal (with appeal fee); CFR 1.114).	or (3) a timely filed	Request for
(c) A reply was received on but it does not constitutional rejection. See 37 CFR 1.85(a) and 1.111. (See	ute a proper reply, or a bona fide atte explanation in box 7 below).	empt at a proper rep	oly, to the non-
(d) ☑ No reply has been received.			
2. Applicant's failure to timely pay the required issue fee an from the mailing date of the Notice of Allowance (PTOL-8	35).	*	
(a) The issue fee and publication fee, if applicable, was , which is after the expiration of the statutory p Allowance (PTOL-85).	s received on (with a Certific eriod for payment of the issue fee (a	ate of Mailing or T nd publication fee)	ransmission dated set in the Notice of
(b) The submitted fee of \$ is insufficient. A balance			
The issue fee required by 37 CFR 1.18 is \$	The publication fee, if required by 37	CFR 1.18(d), is \$_	· ·
(c) The issue fee and publication fee, if applicable, has n			
 Applicant's failure to timely file corrected drawings as req Allowability (PTO-37). 			
(a) Proposed corrected drawings were received on after the expiration of the period for reply.	_ (with a Certificate of Mailing or Tra	nsmission dated), which is
(b) ☐ No corrected drawings have been received.			
4. The letter of express abandonment which is signed by the applicants.	ne attorney or agent of record, the as	signee of the entire	interest, or all of
5. The letter of express abandonment which is signed by a 1.34(a)) upon the filing of a continuing application.	n attorney or agent (acting in a repre	sentative capacity	under 37 CFR
6. The decision by the Board of Patent Appeals and Interfer of the decision has expired and there are no allowed cla	erence rendered on and becaudins.	use the period for se	eeking court review
7. The reason(s) below:		•	
	•		
	J.	Primary Exami Art Unit: 3723	
Petitions to revive under 37 CFR 1.137(a) or (b), or requests to withd minimize any negative effects on patent term.	lraw the holding of abandonment under 3	7 CFR 1.181, should	be promptly filed to
U.S. Patent and Trademark Office	of Abandonment		Part of Paper No. 9

Petition to Revive CFR1.137(a) for David S. Gilbert, Jr. for Slide Lock Wrench consisting of "clear pages" 1 through 11, "marked up" pages 1 through 11 of patent application 09/809/709, copy of letter to James G. Smith dated 4/10/2003 and a copy of the US Express Mail receipt dated 4/09/2003.

